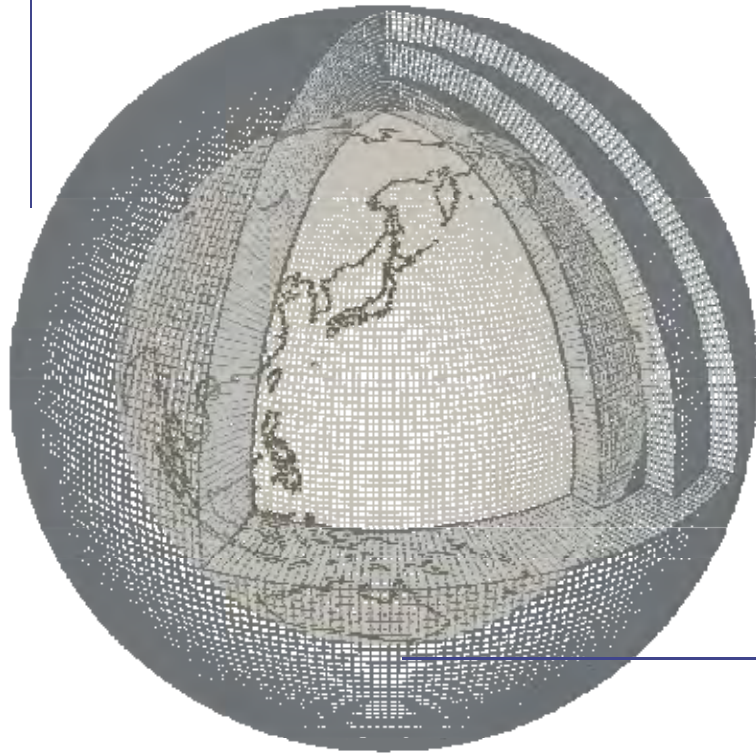


The Impact of Observational data on Numerical Weather Prediction



Hirokatsu Onoda
Numerical Prediction Division, JMA

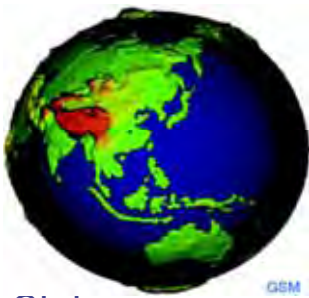
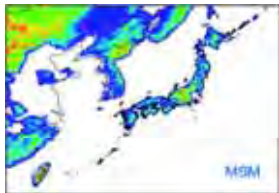
Outline

- Data Analysis system of JMA
in Global Spectral Model (GSM) and Meso-Scale Model (MSM)
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global view of the impact of observations on the quality of the forecast
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Specification of NWP Models

JMA operates the following NWP deterministic models:

- 1) The Global Spectral Model (GSM) for the short and medium range forecast up to nine days ahead to cover the entire globe,
- 2) The Mesoscale Model (MSM) for warnings and the very short-range forecast of precipitation to cover Japan and its surrounding areas.

	Domains and topography	Grid size and/or number of grid, Vertical levels/top	Forecast hours (Initial time)	Initial condition
GSM	 Globe	0.1875 deg. (TL959), 60 / 0.1hPa	84 hours (00,06,18 UTC) 216 hours (12 UTC)	4D-Var analysis
MSM	 Japan and its surrounding areas	5km / 721x577, 50 / 21,800m	15 hours (00,06,12,18 UTC) 33 hours (03,09,15,21 UTC)	4D-Var analysis

Details of data use on NWP system

Observation type	Instrument	Global Analysis 650,000	Mesoscale Analysis 820,000
Conventional 20%	SYNOP	Pressure	Pressure
	AMeDAS*		Rain (Analyzed Rain)
	Ship, Buoy		Pressure
	RAOB	Relative Humidity	Pressure, Wind, Temperature, Relative Humidity
	Aircraft	Wind, Temperature	Wind, Temperature
Ground based remote sensing	Wind profiler	Wind	Wind
	Radar		Radar reflectivity (Analyzed Rain), Doppler velocity
	GPS		Total precipitable water
Satellite 80%	Visible IR radiometer	AMV, Radiance (clear sky)	AMV
	IR MW sounder	Radiance (clear sky)	Radiance (Temperature)
	MW imager	Radiance (clear sky)	Radiance (TPW, Rain rate)
	Scatterometer	Surface wind	Surface wind
	GPS-RO**	Refractivity	

Importance is still high

* Automated Meteorological Data Acquisition System ** GPS radio occultation

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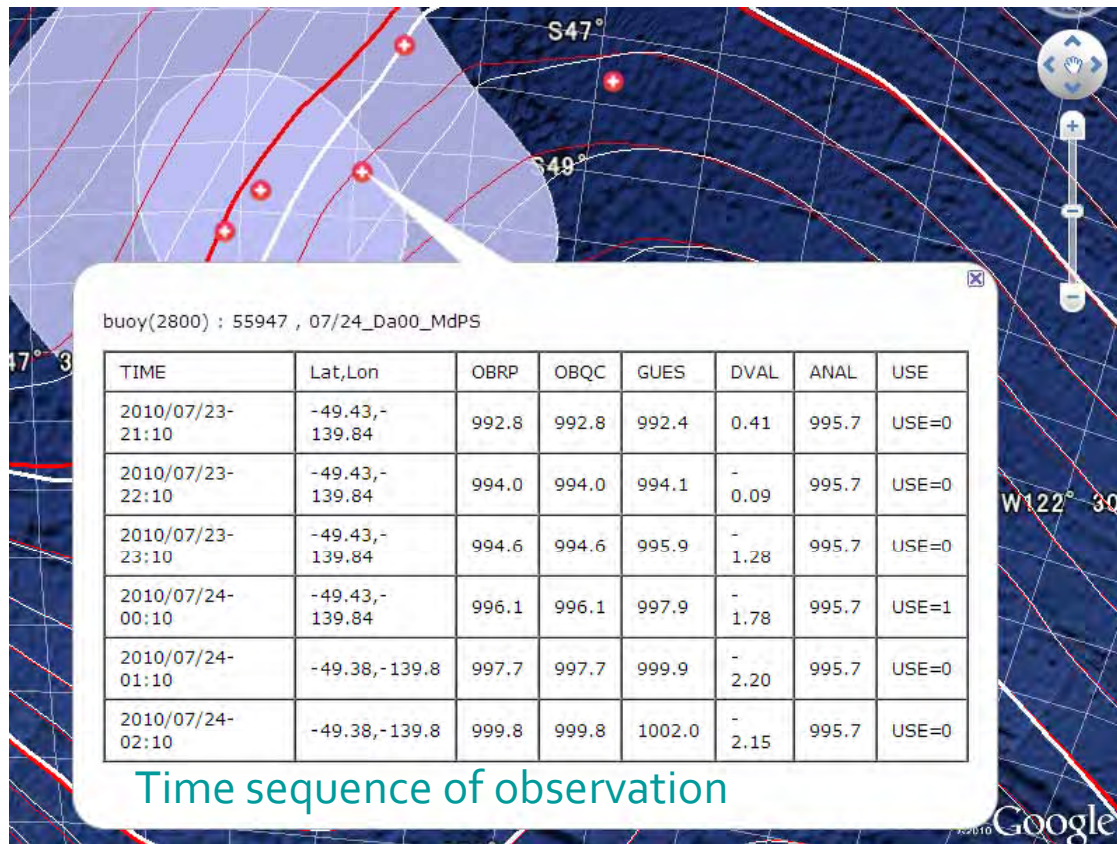
Departure of observation and background

Definition of words

Background : forecast from previous analysis
i.e. in GSM,
12UTC's background is 06UTC's 6-hour forecast.

O-B : (**O**bservation) – (**B**ackground)
usable for an index of the precision
of the forecast or the observation

Basis of Data Analysis system



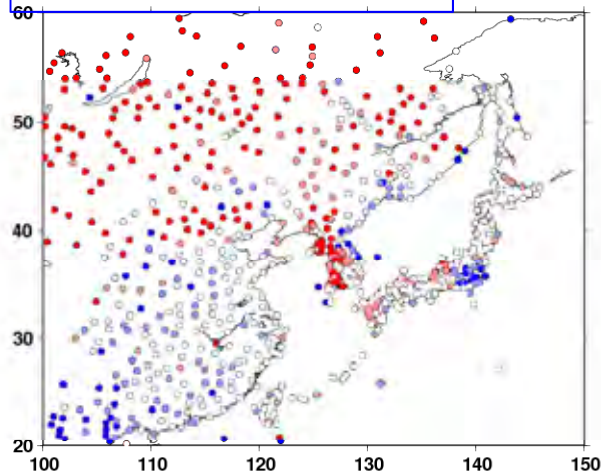
Schematic view of data analysis system (mean sea-level pressure)

In data analysis system, observation revise the error of the model based on departure of observation and background (O-B).

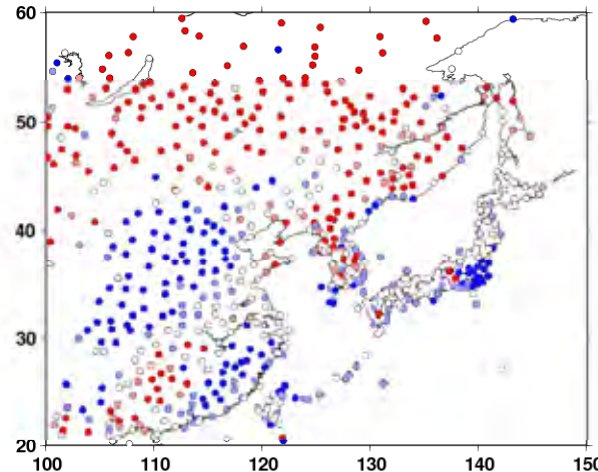
White line : Background (input)
Red point : Observation (input)
Red line : Analysis (output)
Colored area : Increment (output)
*quantity of revision by analysis

Experiment without ground-based conventional observation (SYNOP, Radiosonde) #1

OPERATIONAL



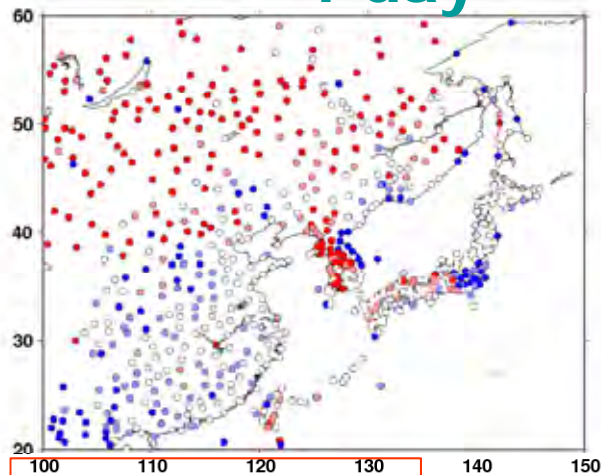
1 day



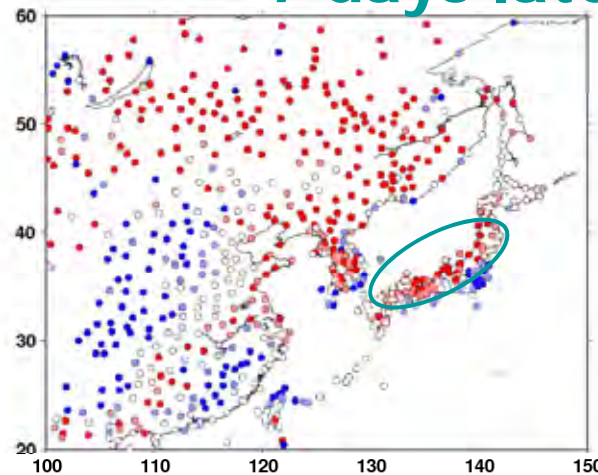
7 days later

Mean Sea-Level pressure O-B at SYNOP stations.

Term of experiment:
from 20th Dec 2009
to 09th Feb 2010



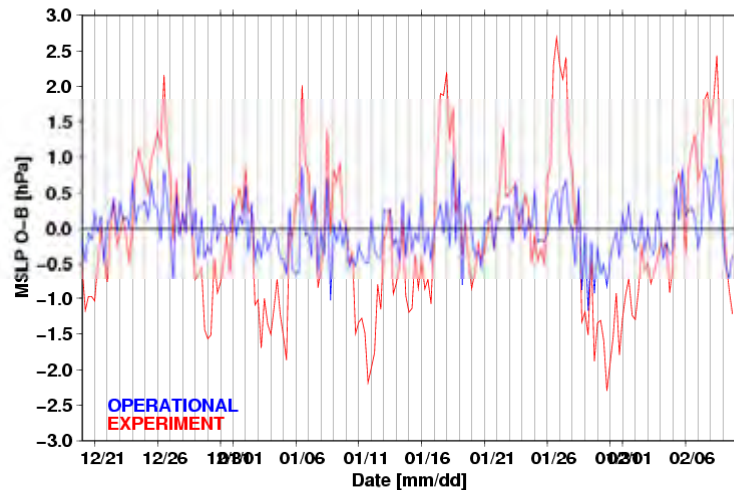
EXPERIMENT



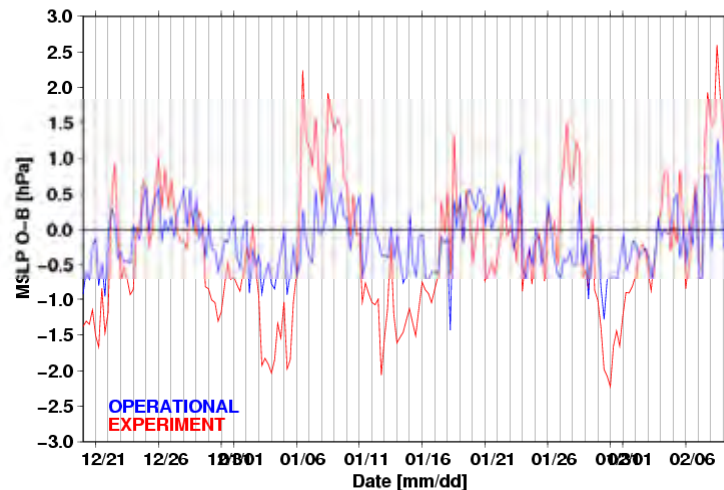
Difference of O-B increased through the analysis-forecast cycle. Continuous observation is important for forecast field.

Experiment without ground-based conventional observation (SYNOP, Radiosonde) #2

Average MSLP O-B of SYNOP stations [TURKMENISTAN]

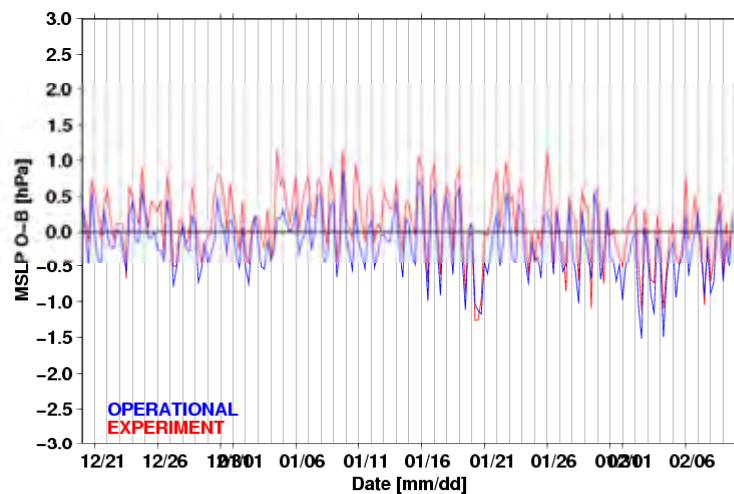


Average MSLP O-B of SYNOP stations [UZBEKISTAN]

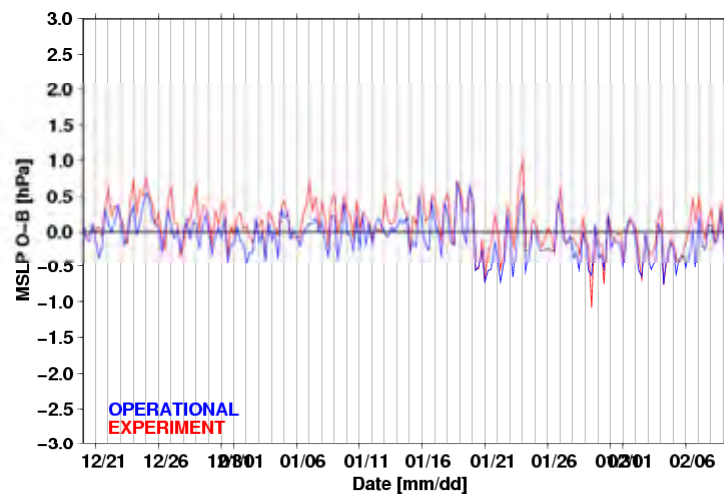


Large difference
between
OPERATIONAL
and
EXPERIMENT

Average MSLP O-B of SYNOP stations [KOREA]



Average MSLP O-B of SYNOP stations [JAPAN]

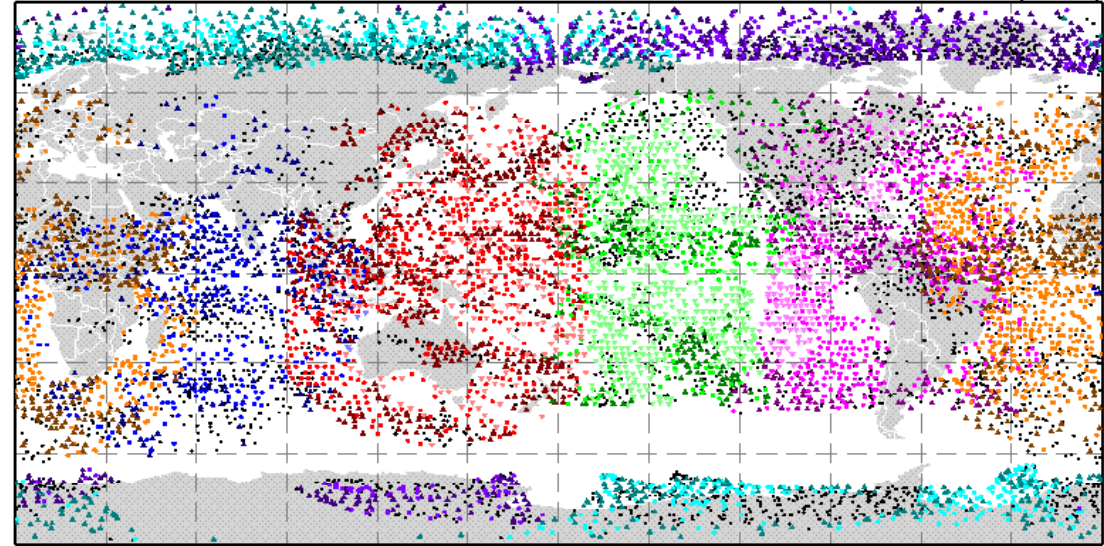


Small difference
between
OPERATIONAL
and
EXPERIMENT

Experiment without ground-based conventional observation (SYNOP, Radiosonde) #3



ATMOSPHERIC MOTION VECTOR 2010/07/21 00:00(UTC)



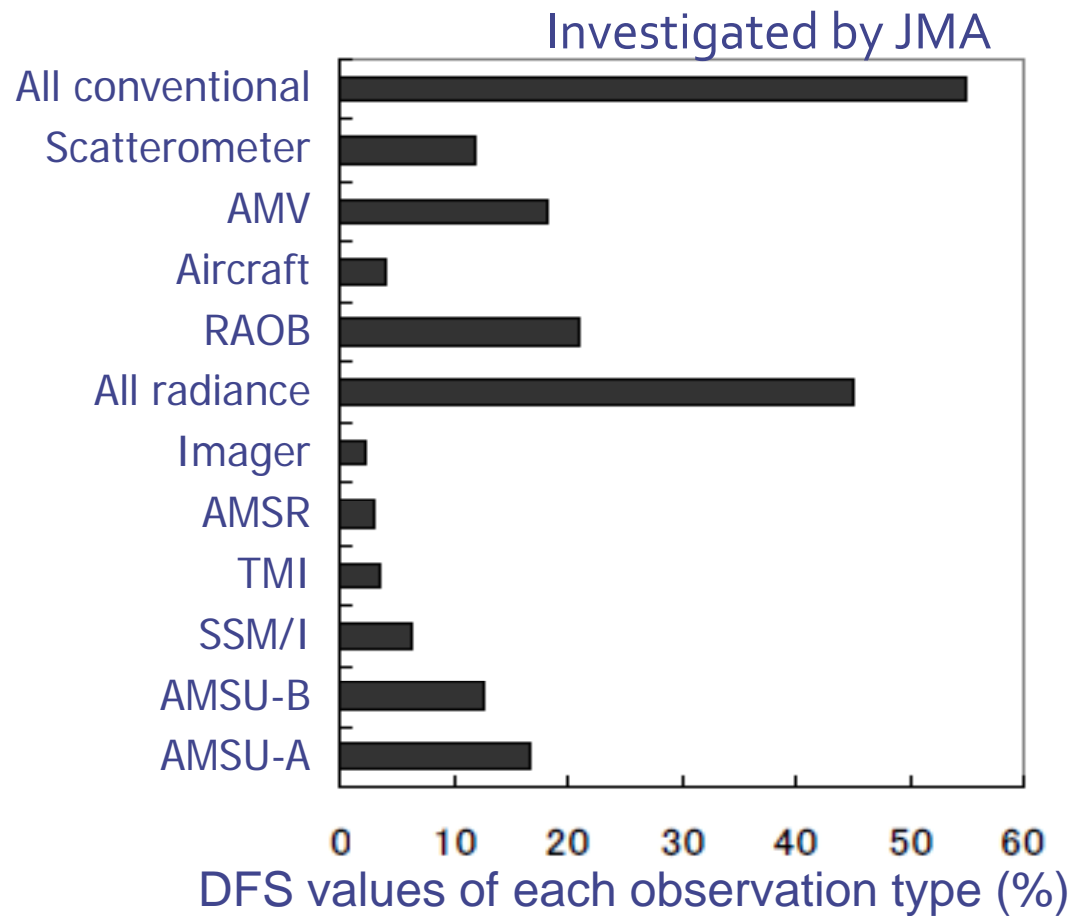
MTSAT-1	GOSE-11	GOSE-13	Meteosat-7	Meteosat-9	Terra	Aqua
IR[●]: 521	IR[●]: 227	IR[●]: 491	IR[●]: 252	IR[●]: 767	IR[●]: 334	IR[●]: 569
VS[▼]: 202	VS[▼]: 546	VS[▼]: 176	VS[▼]: 6	VS[▼]: 5		
WV[▲]: 559	WV[▲]: 220	WV[▲]: 270	WV[▲]: 316	WV[▲]: 507	WV[▲]: 513	WV[▲]: 772
NOUSE[●]: 307	NOUSE[●]: 666	NOUSE[●]: 828	NOUSE[●]: 357	NOUSE[●]: 605	NOUSE[●]: 483	NOUSE[●]: 798
ALL: 1589	ALL: 1659	ALL: 1765	ALL: 931	ALL: 1884	ALL: 1330	ALL: 2139

- Density of the observation point may be important.
- Satellite observation makes the land a weak point.

DFS (Degrees of Freedom for Signal)

Which type of data had the greater influence?

Langland and Baker suggest
to estimate the observation impact.



Large DFS means large
impact to forecast.
Small DFS means small
impact to forecast.

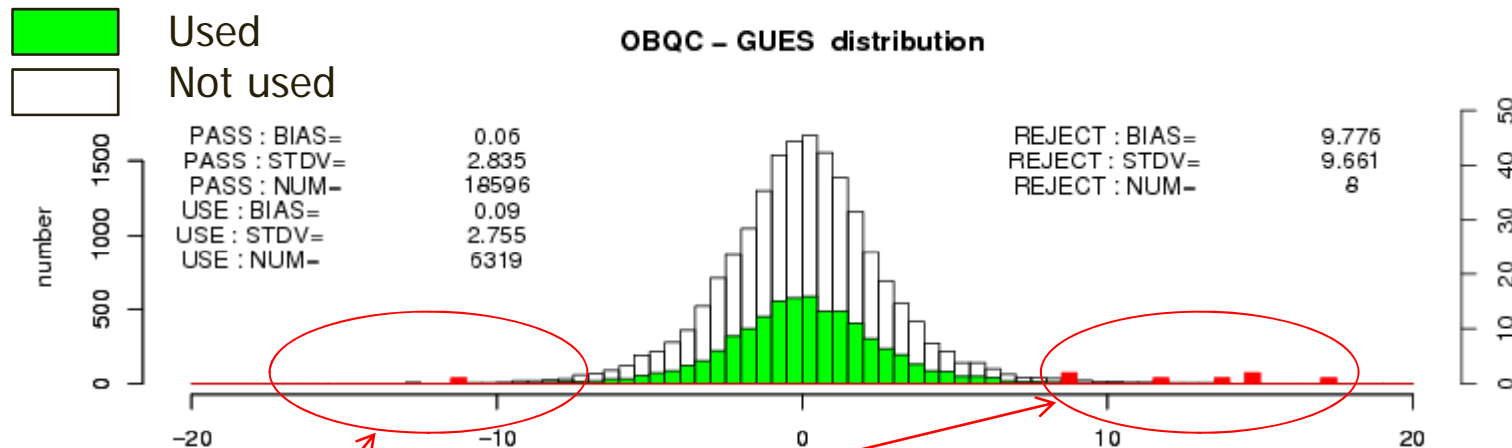
Conventional data still
plays important roll.

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Quality Control (QC) of observational data

Observational data includes false report or deviating from a background.



Δu for Wind Profilers, 1 ~ 10 October 2009, 900 ~ 800hPa

To reject **these data**,
JMA perform **Quality Control (QC)**.

Real-time QC (automatic)
Non real-time QC (manual)

Real-time QC

First Step

- climatologically check
- ship/flight path check
- bias correction
- wind correction
- T lapse rate
- interpolation (T,RH,wind)
- hydrostatic check
- ice (freezing)
- wind shear
- sea-level correction

Etc.

Second Step

- Gross error check
Reject rough error
human error
instrumental malfunction
communication error
etc.
- Spatial consistency check
Compare with surrounding
observations

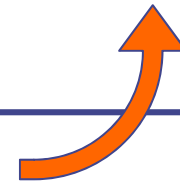
Etc.

Non real-time QC

Sometimes, data of low quality pass real-time QC.
real-time QC is not perfect.

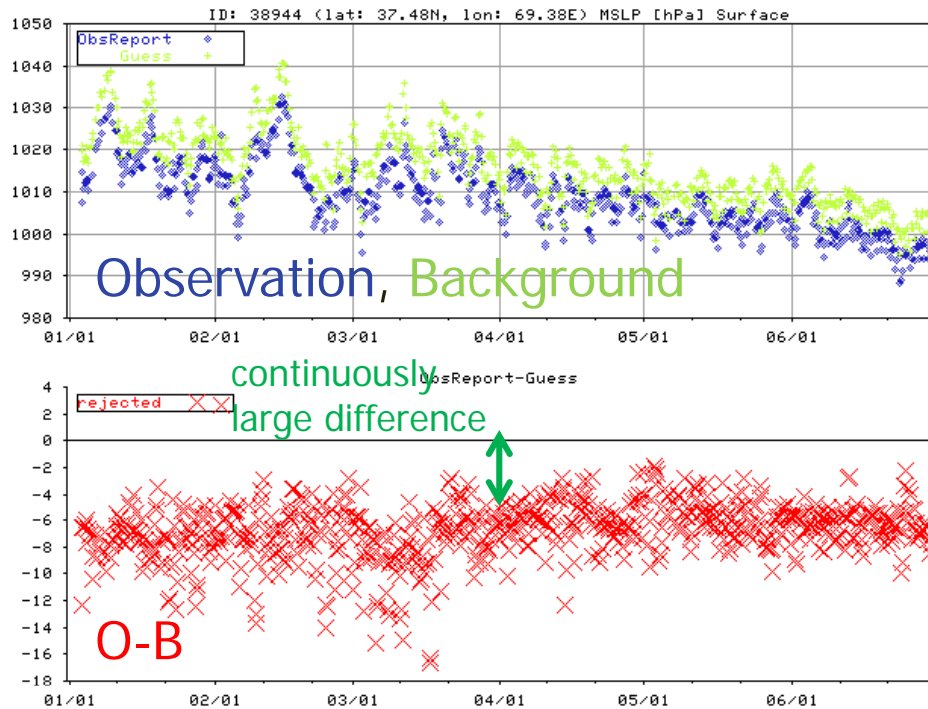
Blacklist is managed for these case.

- Blacklist needs careful monitoring, and is updated when
 - [add]
Platforms (stations, airplanes, ships, etc.) found to report biased or erratic observations
 - [remove]
The quality has returned to an accepted standard
- Blacklisted observations are rejected before real-time QC procedures.



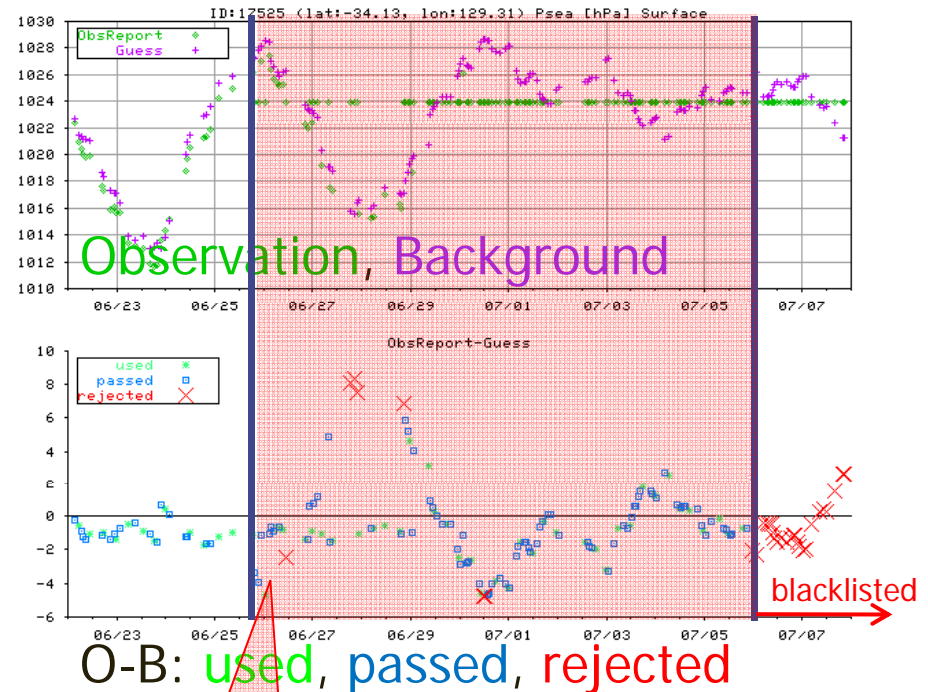
Examples

SYNOP, SHIP, BUOY : trouble of instrumentation



Time sequence of Mean Sea-Level pressure of SYNOP (WMO-ID:38944) from January to June 2010.

Easy case to reject in real-time QC.



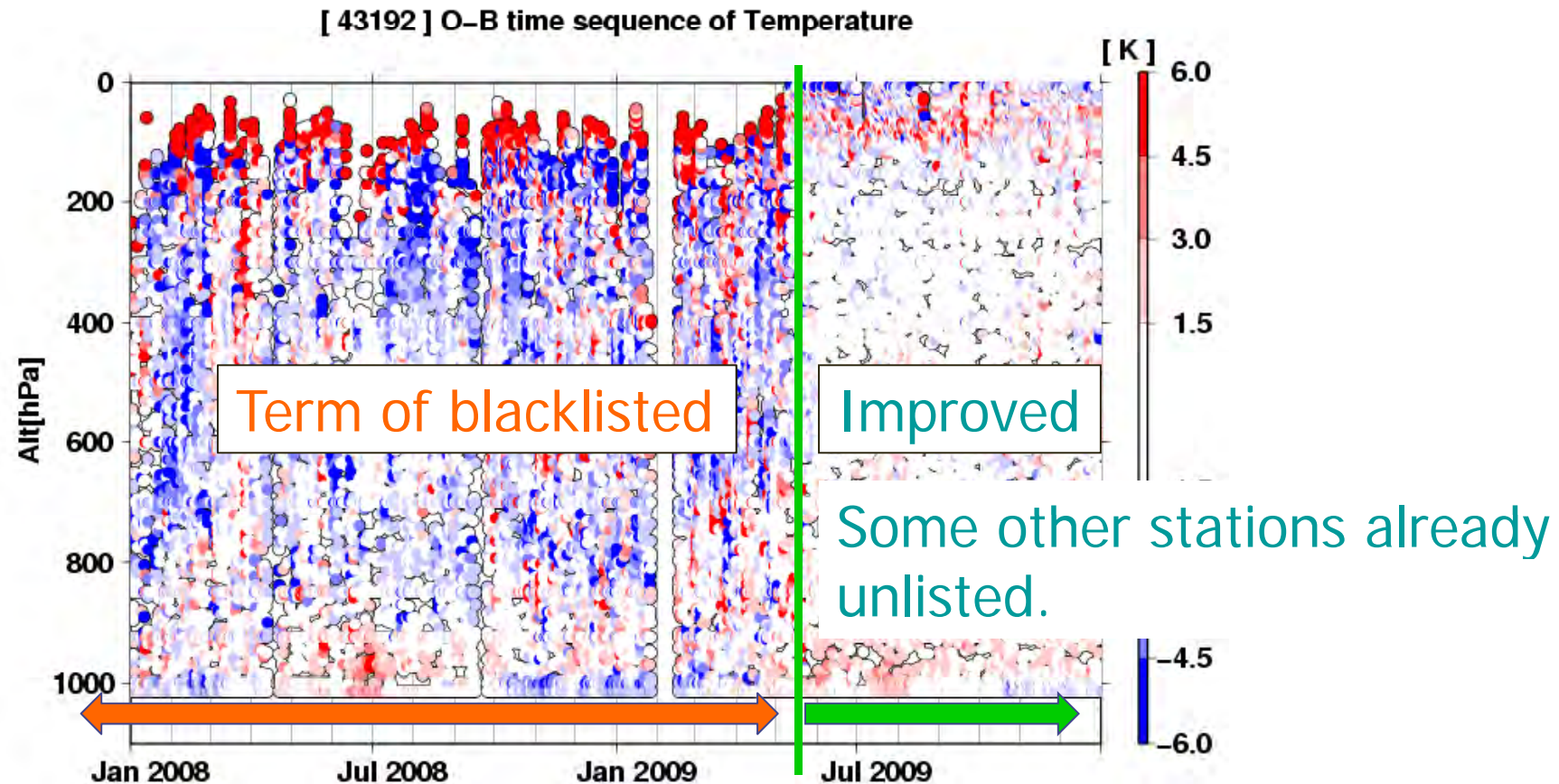
Time sequence of Mean Sea-Level pressure of Buoy (Call sign:17525) from 22nd June to 8th July 2010.

Difficult case to reject in real-time QC.

Inappropriate data were used in operational.

Radiosonde :

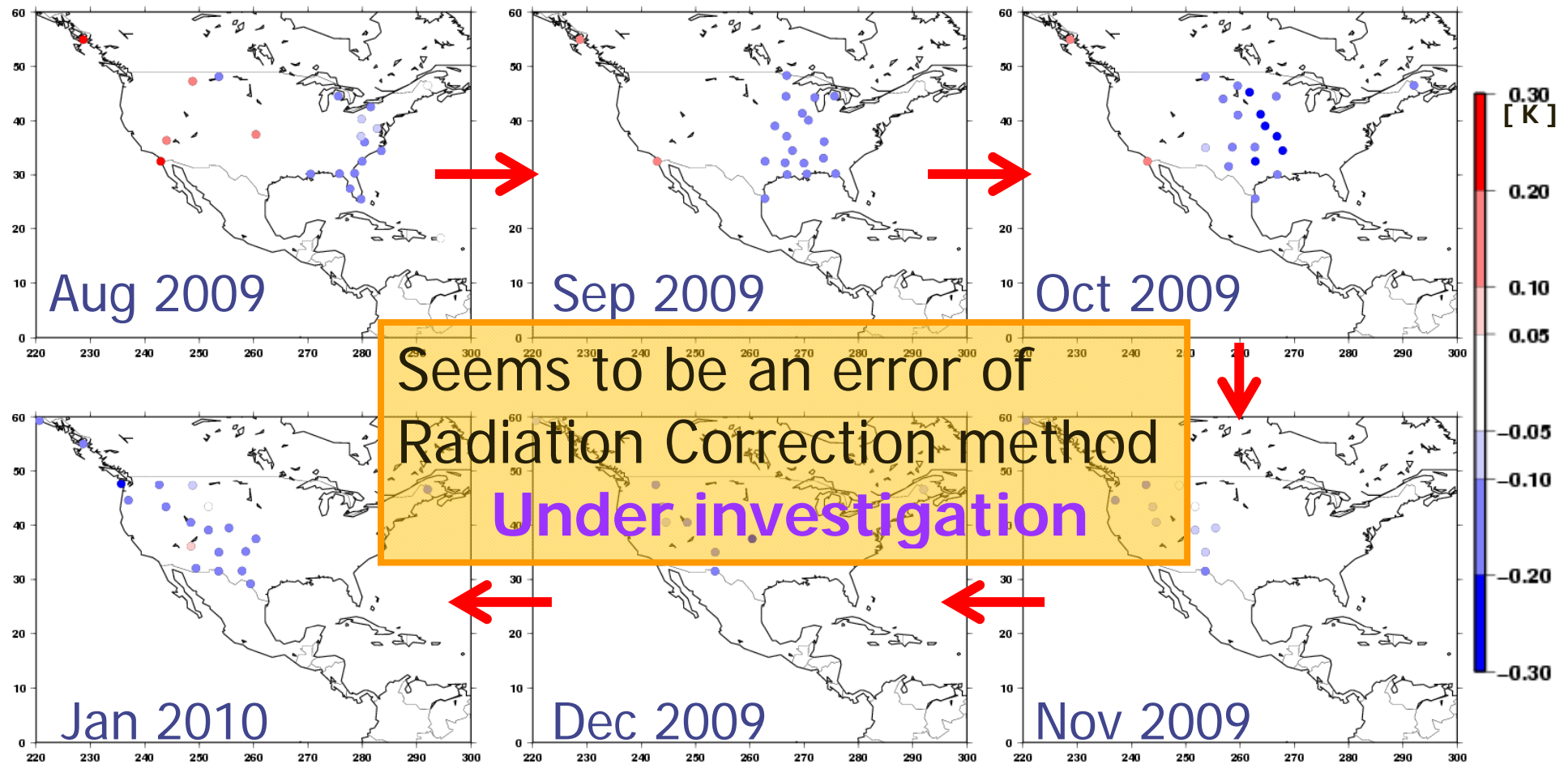
Quality of Indian Radiosonde observations has improved



Time sequence of temperature O-B vertical profile from Jan 2008 to Dec 2009 at WMO-ID:43192 .

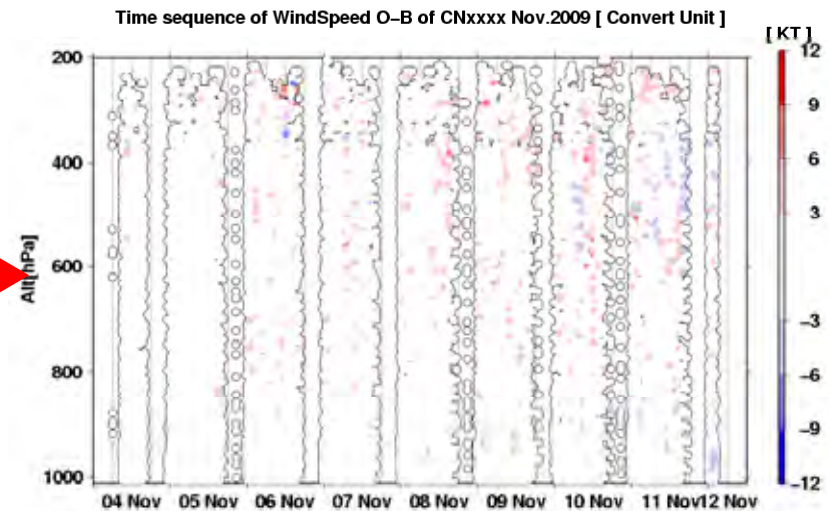
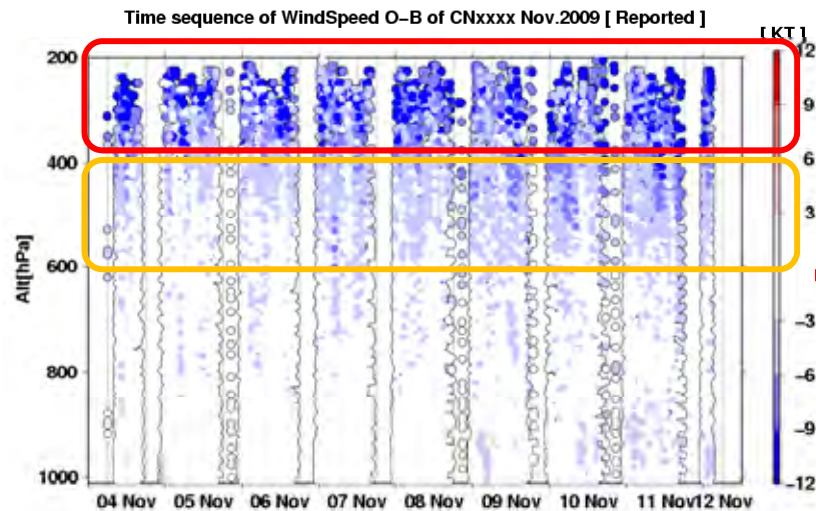
At spring 2009, O-B became small suddenly.
Supplier of instrument has changed.

Radiosonde : Moving bias of US radiosonde observations



Monthly average of T200 O-B from Aug 2009 to Jan 2010.
Negative values (lower observations) moving westward.

Aircraft : Mistake of the report format



Wind speed O-B profile of
CNxxxx (xxxx : number) at China.
There is negative bias in upper air.
Term: 4th – 12th Nov 2009

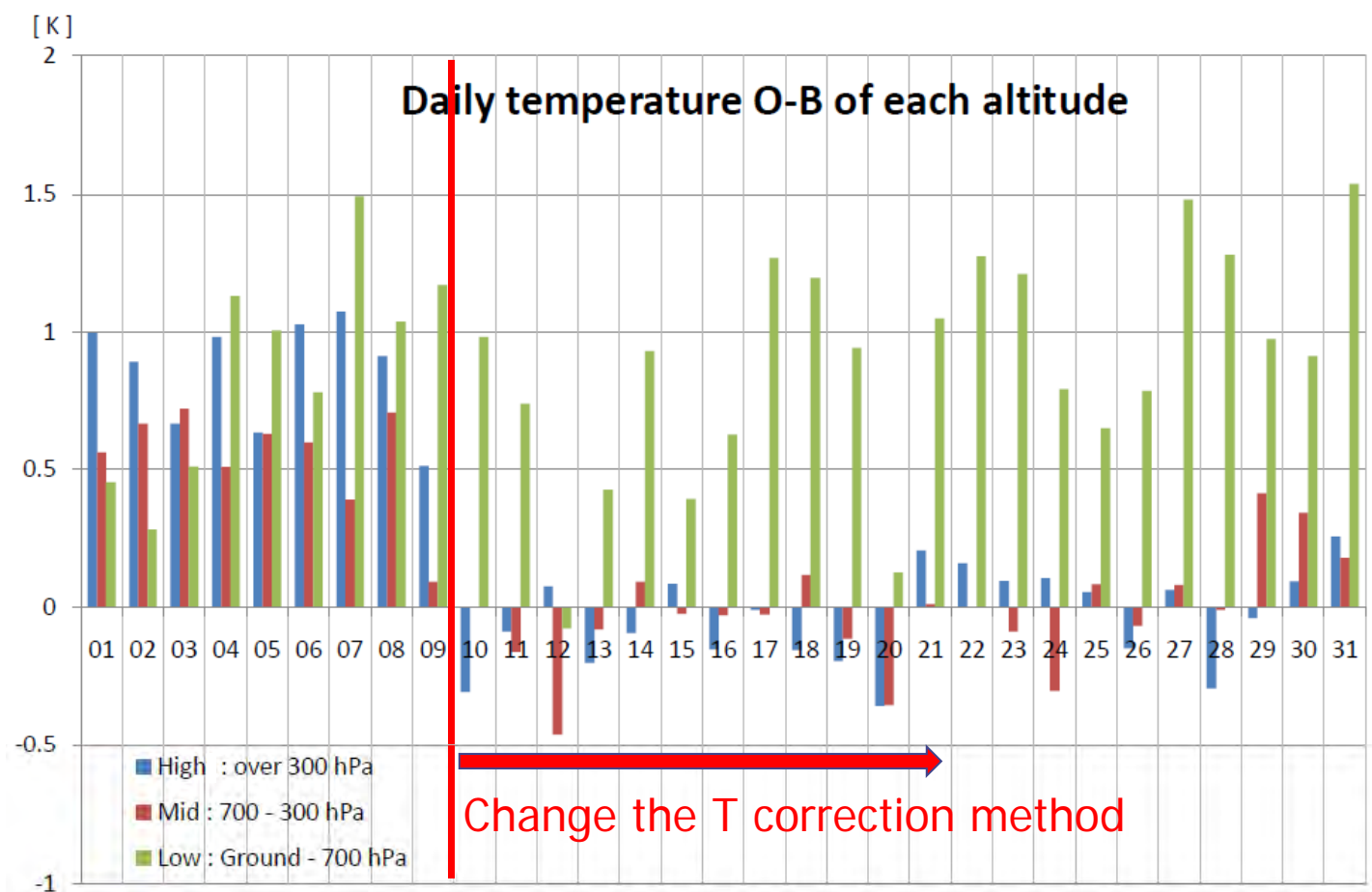
Large biased observation was rejected
Small biased observation was used
in operational system.

By the later investigation:

Convert unit of wind speed
from [m/s] to [Knot].
(Suppose that
reported unit were "m/s".)

Negative bias is disappeared.
The guess might be right.

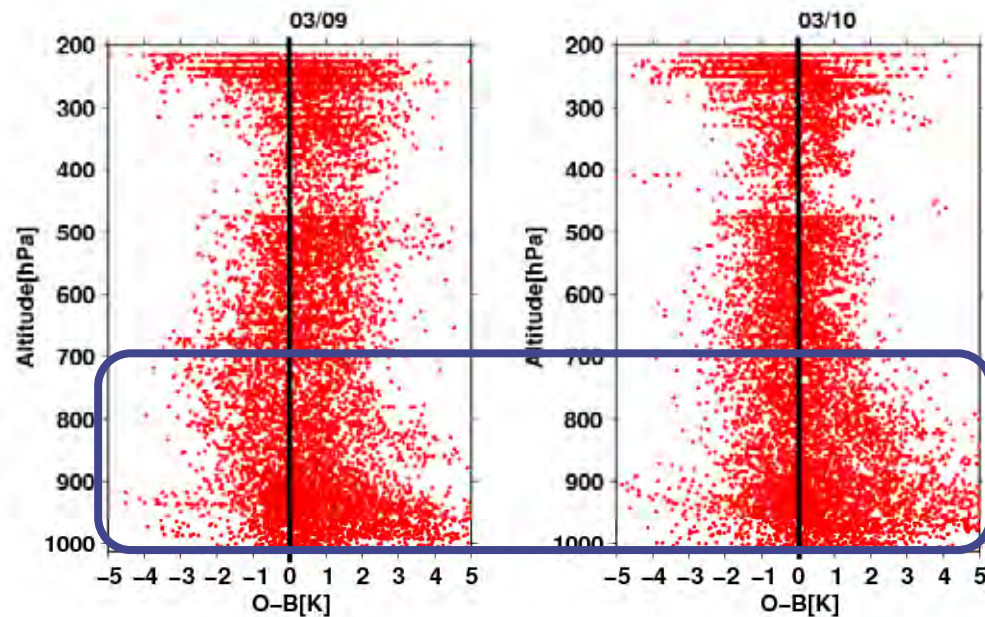
Aircraft : The change of correction method by airline



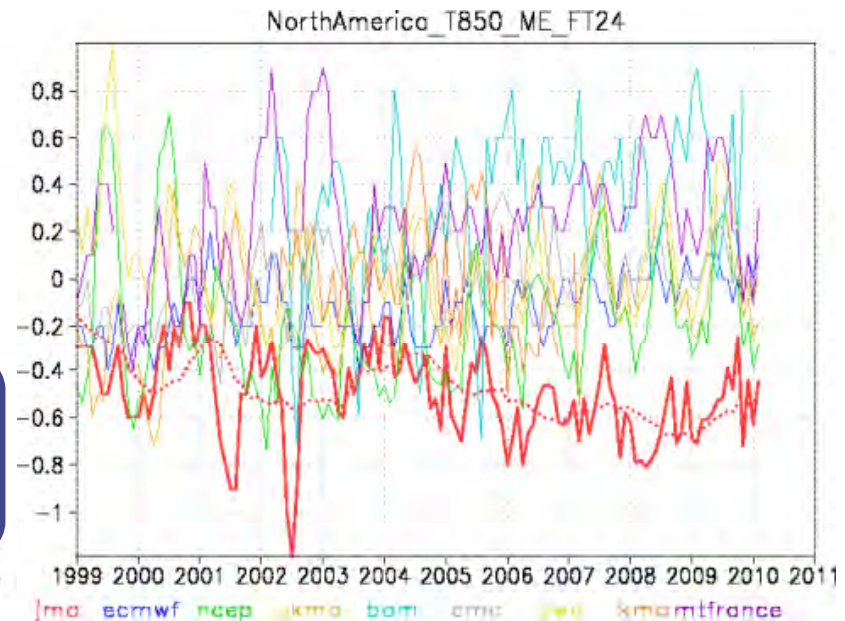
Southwest Airline (SWA; USA) changed the method of temperature correction from 10th Mar 2010. 86 airplanes correspond to this case.

Improvement of O-B is found especially High and Middle(Mid) altitude.

Is it Observation error or Model error ? #1



Temperature O-B scatter plot at 9th and 10th March 2010.
Many points came to gather in the graph center.



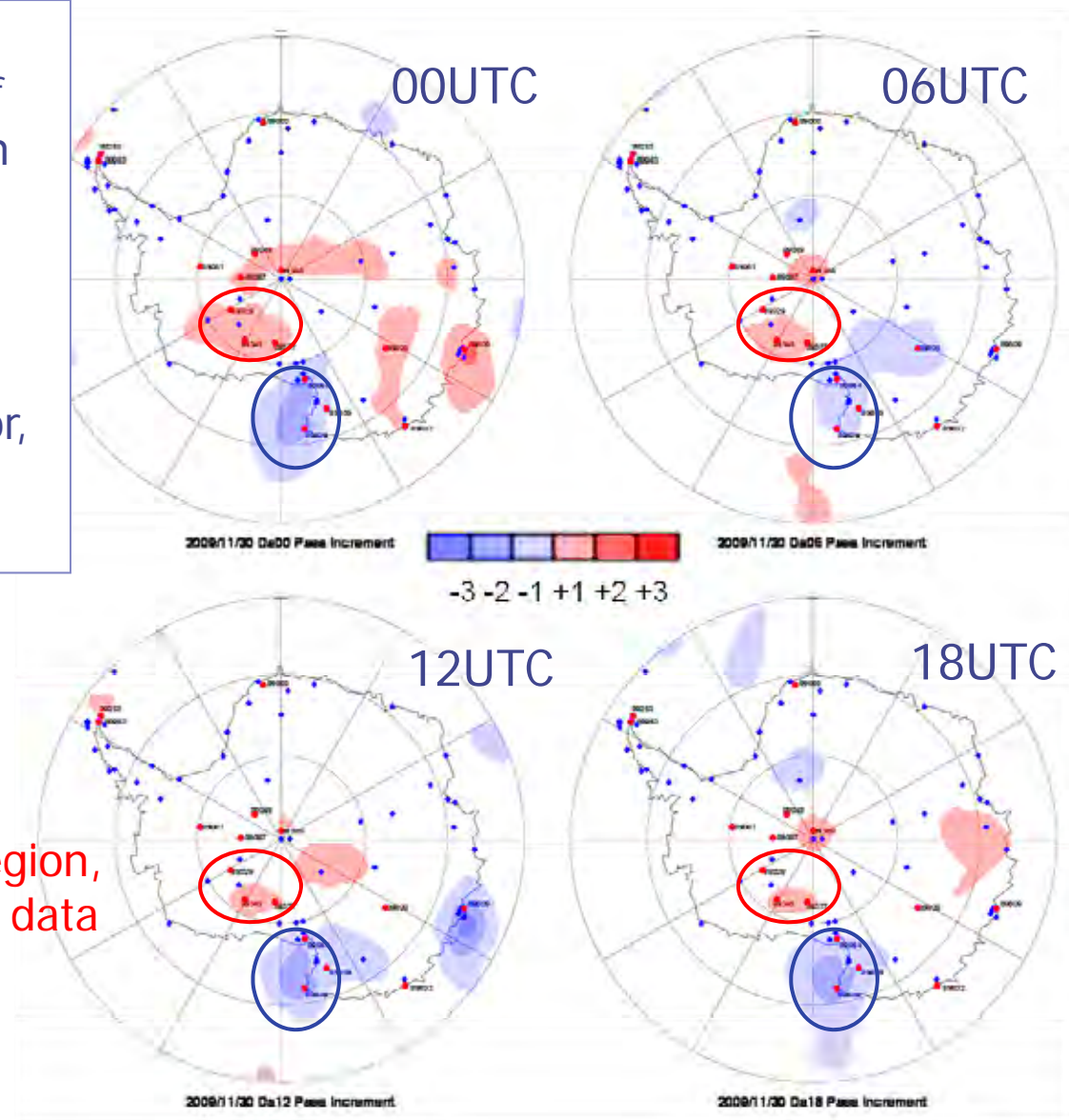
Inter-comparison of T850 at North America for forecast time 24h.
JMA (red line) may have lower bias of temperature.

There are not many changes at lower altitude.

Is it Observation error or Model error ? #2

Increment (quantity of revision by analysis) map of Mean Sea-Level pressure on Antarctica at 00,06,12,18 UTC analysis, 30th Nov 2009.

It seems to be a model error, because some stations suggest similar O-B.



Antarctica is data sparse region, real-time QC hard to reject data with large difference from background.

Summary

- The ratio of conventional data has become **small**, but the importance is still **high**.
- **Continuous observation** and **the maintenance of the network** are necessary.
- **QC** plays an essential part in maintaining the quality of the initial value and forecast field.
- QC is composed real-time and non real-time QC.
Blacklist is kept for non real-time QC.
Important to be careful to **the changes of the data tendency**.
The correct format and **unbiased** reporting is needed.
- Difficult to discriminate
whether **errors are related to observation or to the model**.

Request to Observation from NWP system

Good product of weather forecasting needs good analysis.

Good analysis needs good observation.

Good observation needs the cooperation of many people.

- We need to keep **high quality** observation **for NWP system**.
 - Continuous observation
 - Maintenance of the dense observation network
 - Recovery from instrumental malfunction (as soon as possible)
 - The correct format reporting
 - Unbiased observation
 - Information when the station changes (latitude, altitude, height ...)
 - * information of position is extremely important.
 - Information of the instrumental changes
- High quality observation **enables to be better forecast**.
 - enables to make good analysis
 - enables to use inspection of models

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Data monitoring report

JMA publishes following reports ;

- Monthly Global Monitoring Report

JMA reports suspected observations of low quality through our NWP system once a month.

- Report on the Quality of Land Surface Observations in Region II (Asia)

RSMC Tokyo publishes it in a half year as a lead center for monitoring the quality of land surface observations.

**Using these reports,
we want you to make use for maintenance of
the high quality observation.**

website

These reports are shown in following Website.
Anyone can access without a password.

<http://qc.kishou.go.jp>

Top

Numerical Prediction Division / Japan Meteorological Agency

Data Monitoring

Monitoring Report

- [Monthly Monitoring Report](#)
- [6-Monthly Monitoring Report](#)

Satellite Data Monitoring

- [Time Series of Statistics on Satellite Wind](#)
- [Time Series of Statistics on Satellite Radiance](#)

[Any comments are welcomed.](#)

[Monthly Monitoring Report](#)

[6-Monthly Monitoring Report](#)

The primary information on the quality of observation is based on the differences between the observed data and the corresponding first-guess field (e.g., from the global model). These background information is useful to check the quality but some areas such as steep orography or with the first guess can be questionable. The results should be interpreted with care.

Satellite Data Monitoring

[Time Series of Statistics on Satellite Wind](#)

[Time Series of Statistics on Satellite Radiance](#)

WMO IDENT	ELEV (m)	ELE-MENT	LEVEL	NUM OBS	NUM GRS	% GRS	% REJ	SD	BIAS	RMS
15533	26	MSLP	SUR	120	0	0	0	0.8	-4.3	4.4
37756	755	MSLP	SUR	94	0	0	24	1.8	4.5	4.8
38944	448	MSLP	SUR	117	0	0	100	1.3	-6.3	6.4
40009	349	MSLP	SUR	112	1	1	0	1.5	-4.2	4.5
40739	1349	MSLP	SUR	104	0	0	0	2.2	-4.2	4.7
40747	1373	MSLP	SUR	48	0	0	2	2.1	-4.2	4.7
40754	1191	MSLP	SUR	106	0	0	2	1.9	-4.3	4.7
40769	1703	MSLP	SUR	88	0	0	2	3.5	-4.0	5.3
40783	2022	MSLP	SUR	48	0	0	2	3.4	-4.6	5.7
40800	1550	MSLP	SUR	102	0	0	2	3.2	-5.0	5.9

Thank you for your attention.

Please be careful to avoid heat strokes.

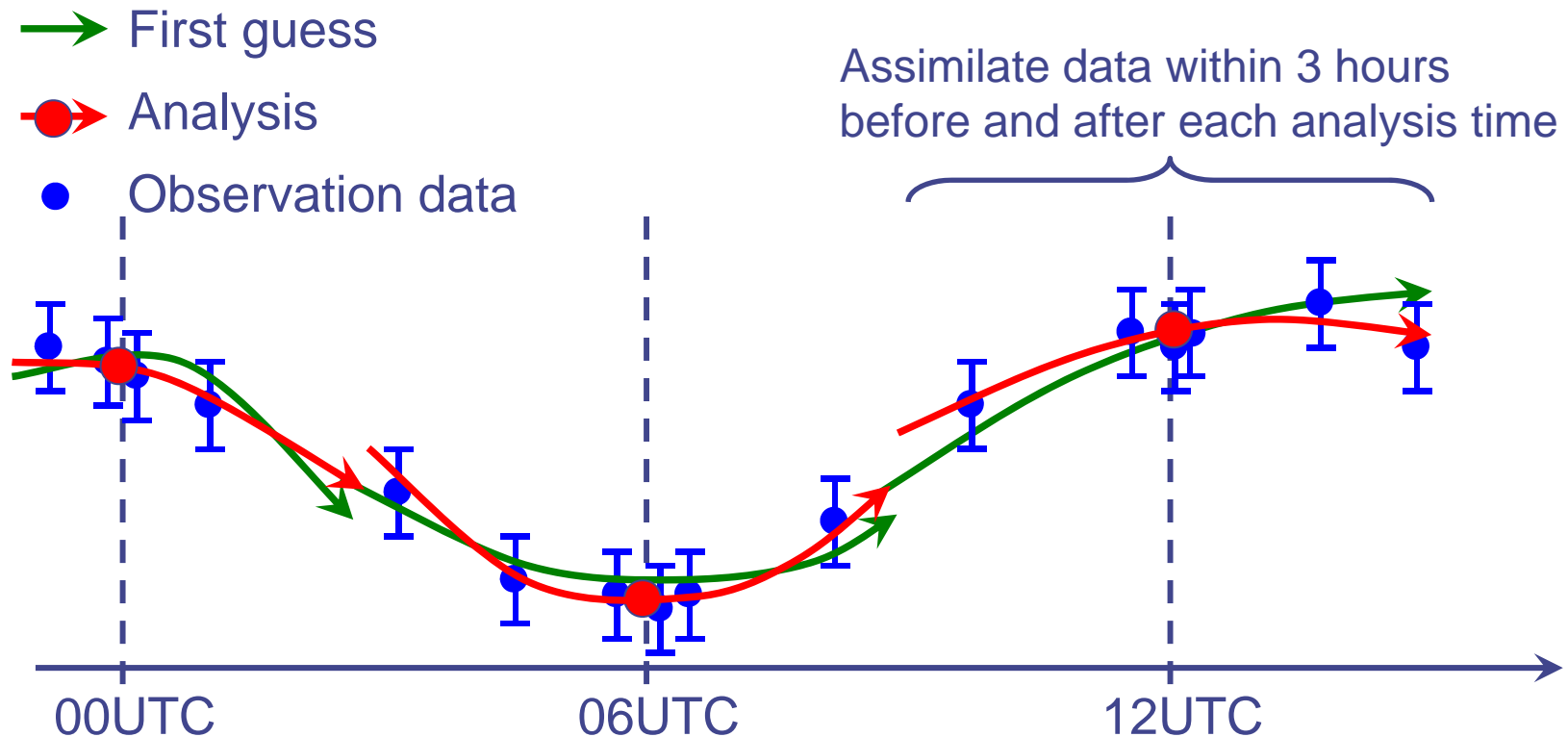


Contact us

E-mail : qc@naps.kishou.go.jp

Additional slides

Four-Dimensional Variational Analysis (4D-Var)



Forecast from previous analysis is used as a first guess.

Departure between model trajectory and observations over 6-hour assimilation window are measured (cost function).

Then, model trajectory that minimizes the departure is sought. Analyzed field at target analysis time is obtained as forecast field at that time.

Observation Impact Methodology (Langland and Baker, 2004)

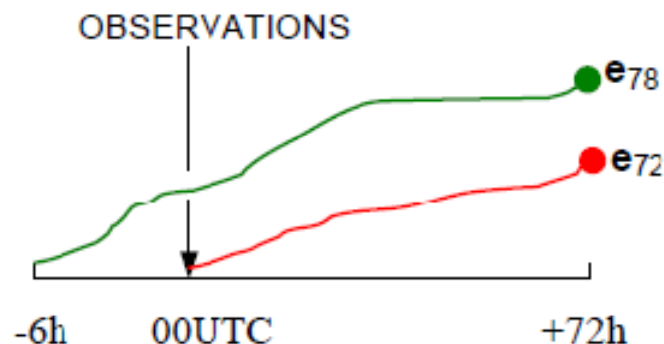


Fig. 1: Observations are assimilated at 00UTC, creating ICs for a new trajectory, which has forecast error e_{72} . The old trajectory starts from 18UTC (-6h), and has forecast error e_{78} . It also provides the background for the analysis at 00UTC.

Observations are assimilated in a 6-h update cycle. If there are no observations at 00UTC, e_{72} will be equal to e_{78} .

The difference in forecast error norms, $(e_{78} - e_{72})$, is due to the combined impact of all observations assimilated at 00UTC

Using sensitivity gradients from two forecast trajectories, we can estimate the forecast error difference, $^{\text{TM}}\mathbf{e}_f = e_{72} - e_{78}$, using following equation.

$$\delta \mathbf{e}_f = \left\langle (\mathbf{y} - \mathbf{H}\mathbf{x}_b), \frac{\partial J_{72/78}}{\partial \mathbf{y}} \right\rangle$$

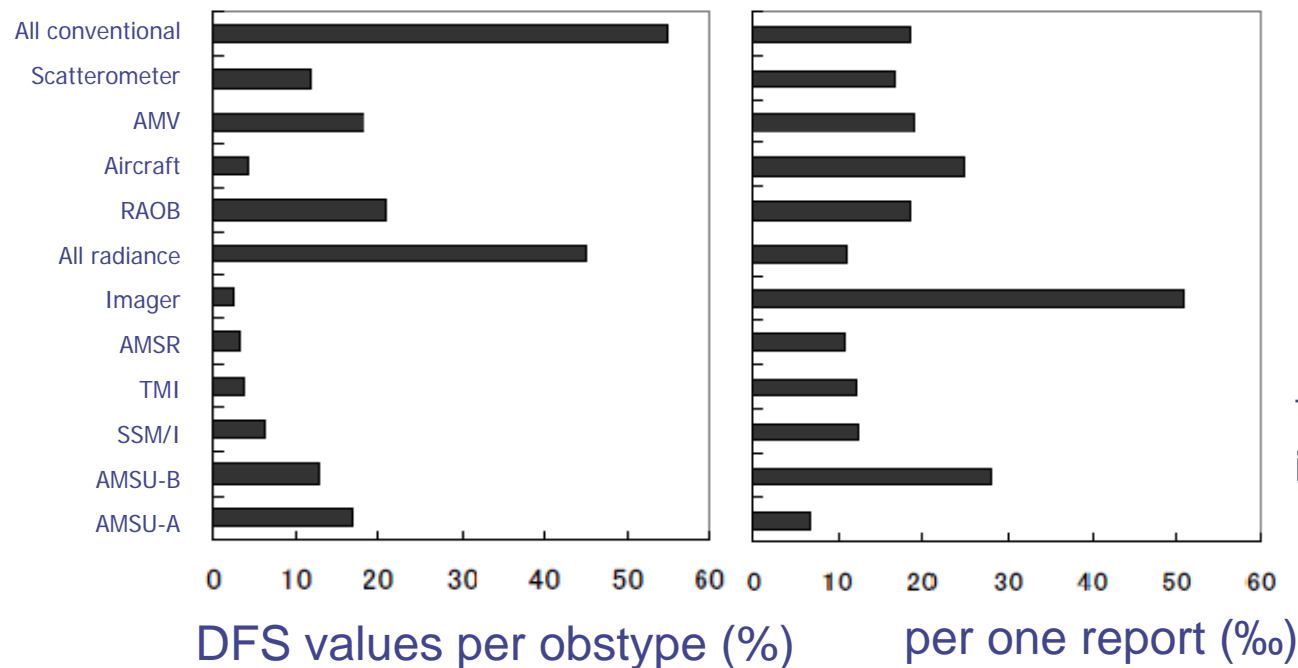
The quantity $(\mathbf{y} - \mathbf{H}\mathbf{x}_b)$ is the observation departure from the background state, and \mathbf{H} is an operator that performs spatial interpolation of the background into observation space.

DFS (Degrees of Freedom for Signal)

The global observation impact can be considered as the sum of contributions made by all individual observations.

Best Linear Unbiased Estimator (BLUE) approach ;

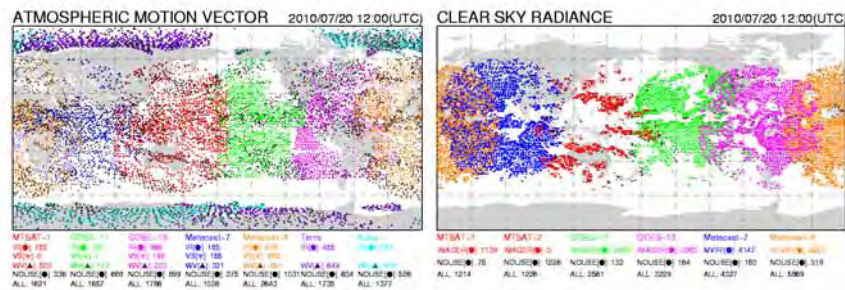
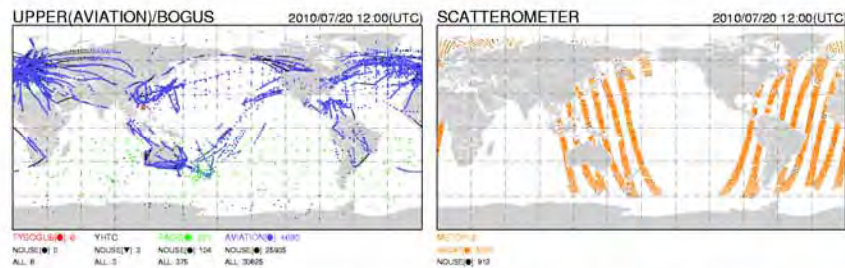
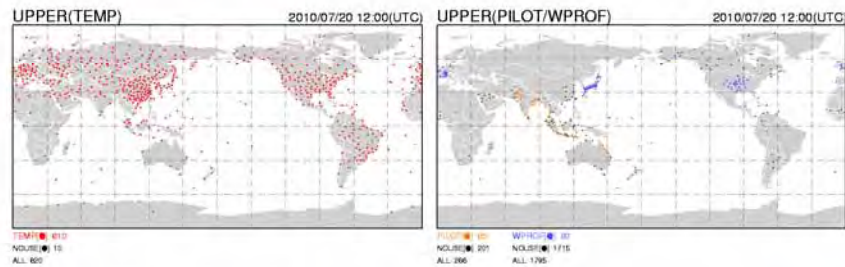
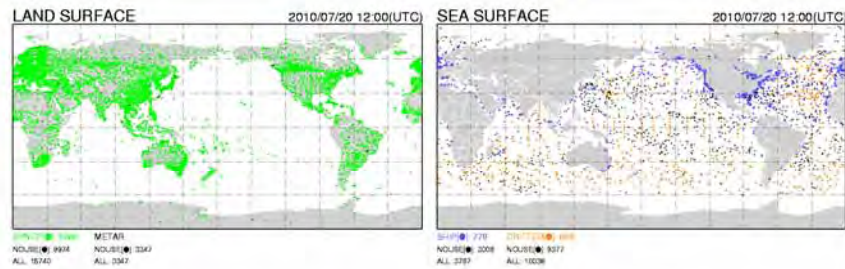
- Define a linear estimator
- Impose the condition to be unbiased



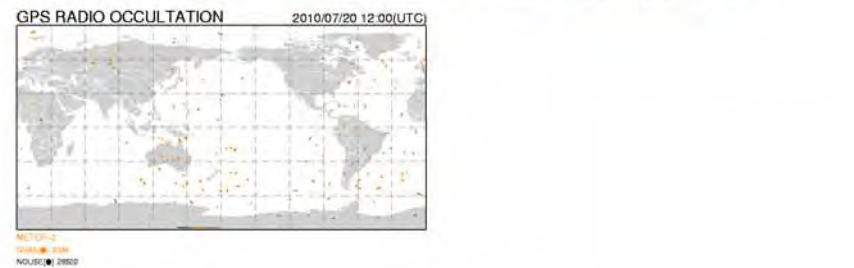
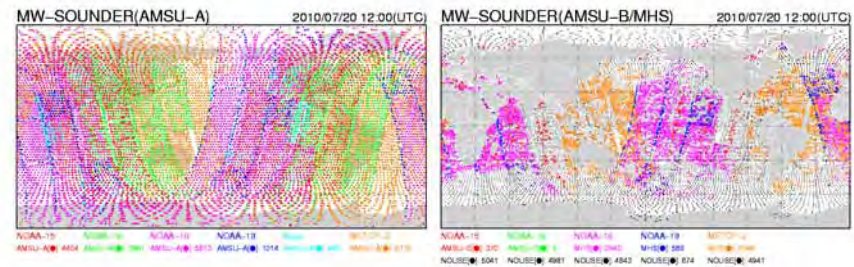
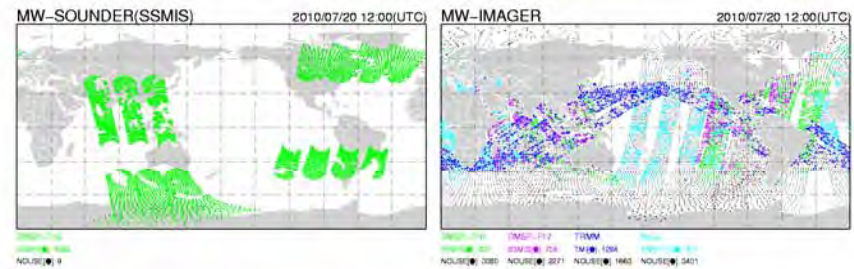
These results were investigated in JMA (Ishibashi, JMA)

Data coverage map (global)

JMA GLOBAL ANALYSIS - DATA COVERAGE MAP - 1 (Da12ps): 2010/07/20 12:00(UTC)



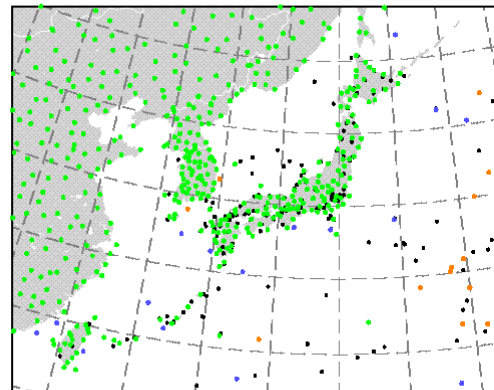
JMA GLOBAL ANALYSIS - DATA COVERAGE MAP - 2 (Da2ps): 2010/07/20 12:00(UTC)



Data coverage map (regional)

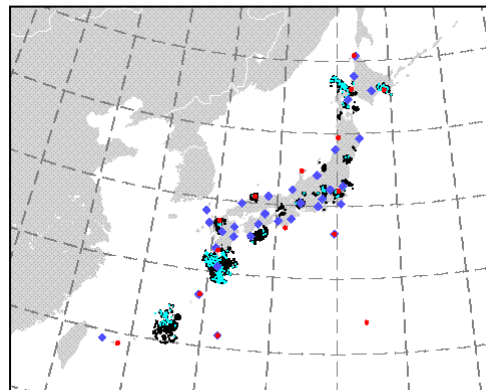
JMA MESO ANALYSIS – DATA COVERAGE MAP (Ma12ps): 2010/07/20 12:00(UTC)

CONVENTIONAL SURF



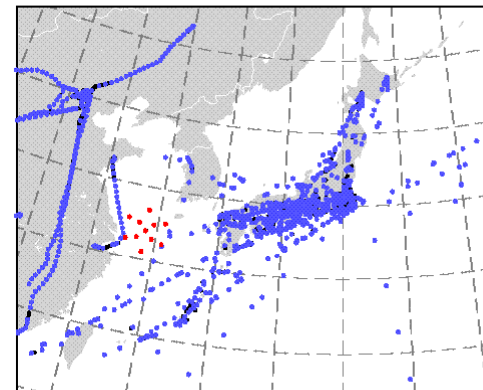
SYNOP[●]: 722 METAR SHIP[●]: 16 DRIFTER[●]: 22
 NOUSE[●]: 27 NOUSE[●]: 1695 NOUSE[●]: 3 NOUSE[●]: 87
 ALL: 749 ALL: 1695 ALL: 19 ALL: 109

CONVENTIONAL UPPER



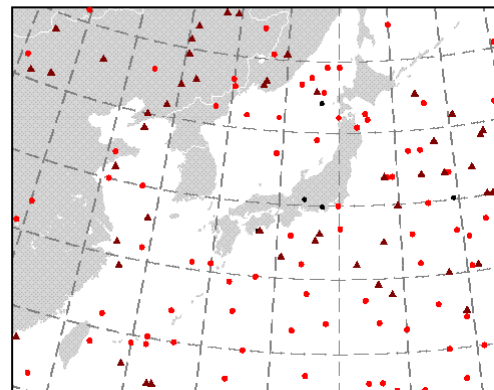
TEMP[●]: 15 PILOT[●]: 0 WPROF[●]: 94 DPR[●]: 305
 NOUSE[●]: 0 NOUSE[●]: 0 NOUSE[●]: 500 NOUSE[●]: 25881
 ALL: 15 ALL: 0 ALL: 594 ALL: 26186

CONVENTIONAL OTHERS



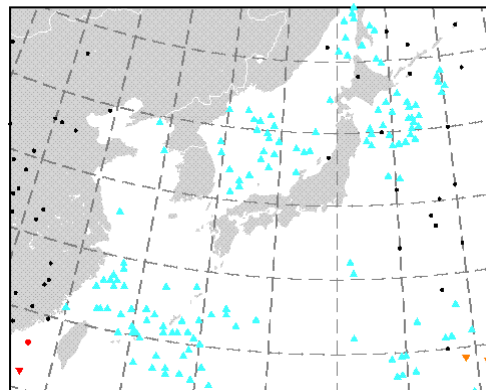
TYBOGUS[●]: 11 YHTC NOUSE[●]: 2836
 NOUSE[●]: 0 NOUSE[●]: 1 NOUSE[●]: 1224
 ALL: 11 ALL: 1 ALL: 4060

AMV / SCATTEROMETER



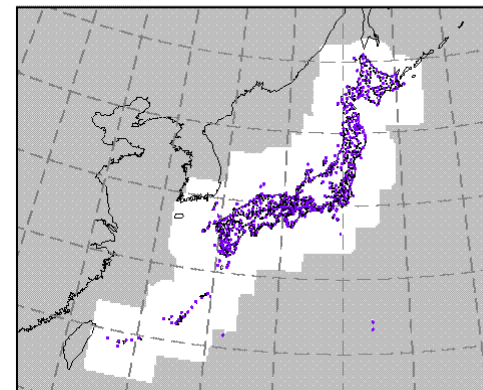
MTSAT-1
 IR[●]: 78
 VS[●]: 0
 WV[▲]: 50
 NOUSE[●]: 5
 ALL: 133

MW-SOUNDER



NOAA-15 NOAA-17 NOAA-18 NOAA-19 METOP-2
 SATEM[●]: 1 SATEM[●]: 0 SATEM[●]: 0 SATEM[●]: 0 SATEM[●]: 0
 ATOVS[▼]: 1 ATOVS[▼]: 0 ATOVS[▼]: 0 ATOVS[▼]: 0 ATOVS[▼]: 2
 MSC[▲]: 0 MSC[▲]: 138 MSC[▲]: 0 MSC[▲]: 0 MSC[▲]: 0
 NOUSE[●]: 20 NOUSE[●]: 3 NOUSE[●]: 19 NOUSE[●]: 19 NOUSE[●]: 19
 ALL: 22 ALL: 141 ALL: 21 ALL: 21 ALL: 21

MW-IMAGER / GPS / R/A

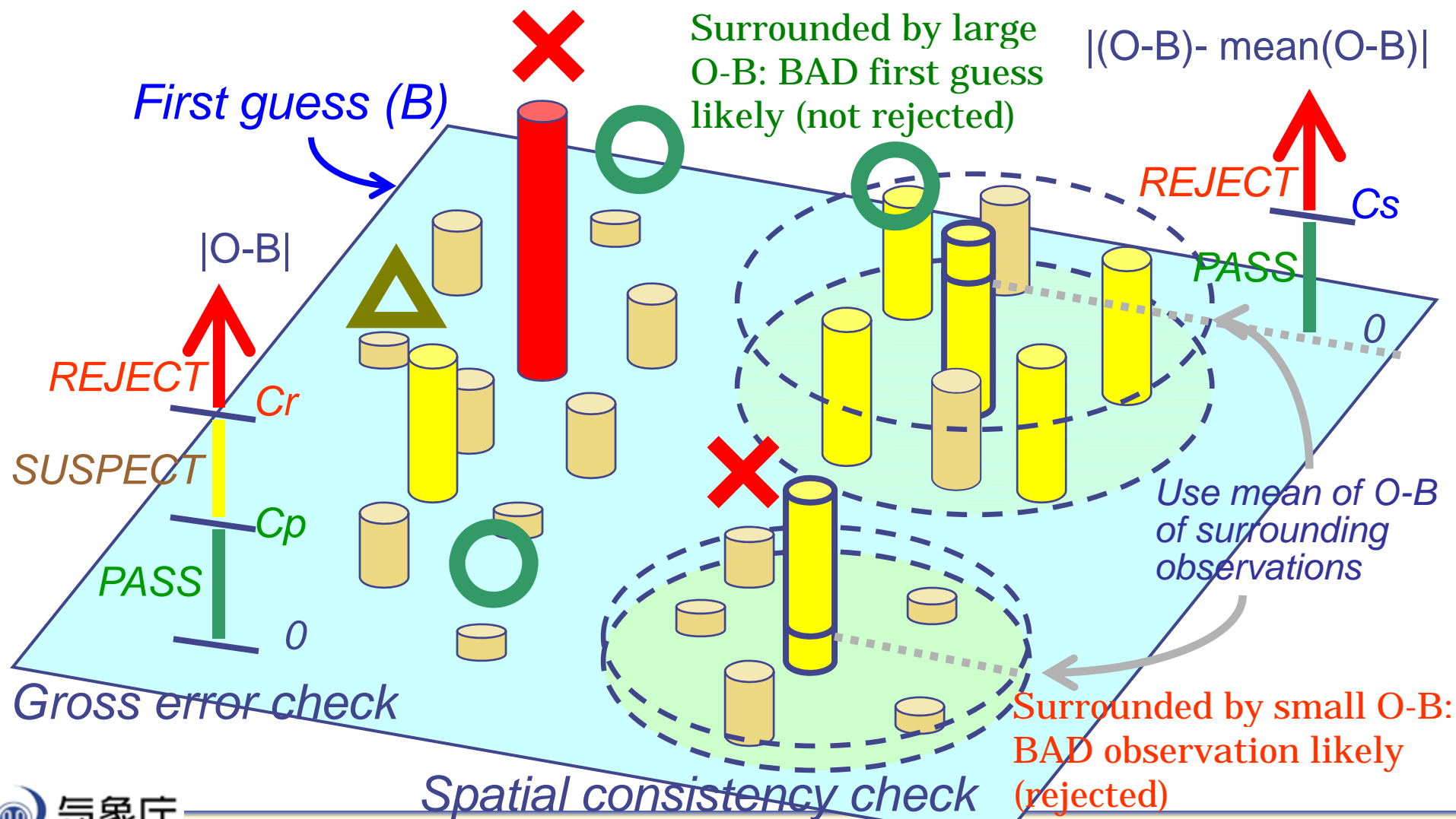


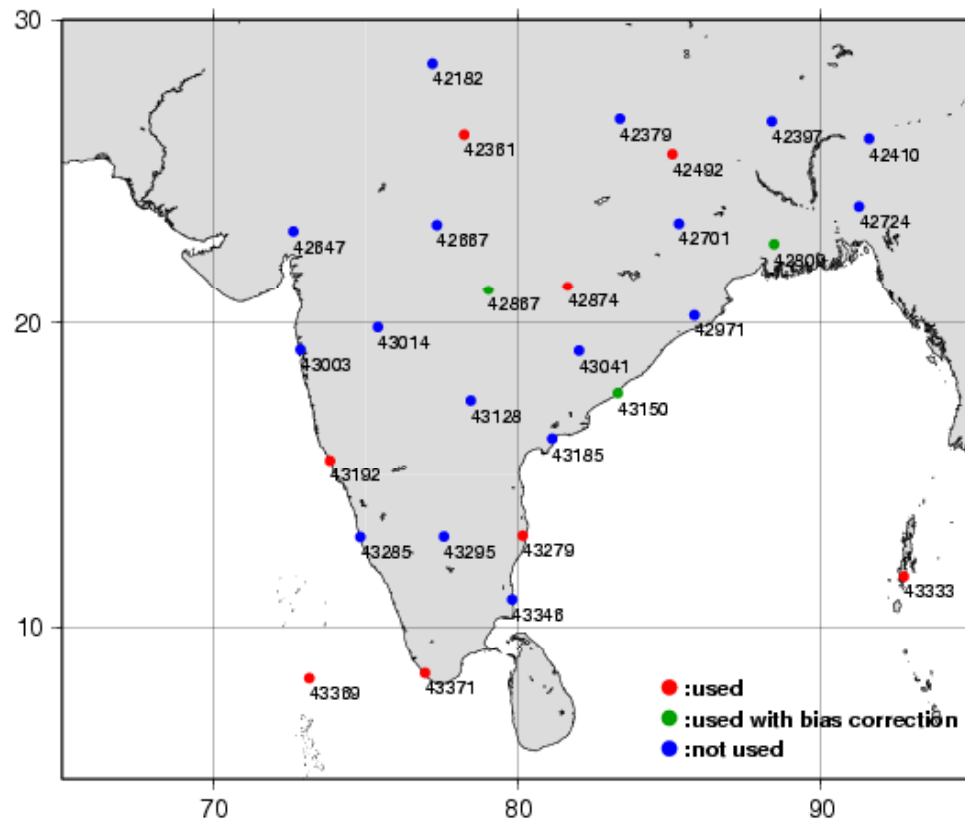
TRMM Aqua NO_RAIN GPS
 [●]: 980
 NOUSE[●]: 1874
 ALL: 2854

Gross error check, Spatial consistency check

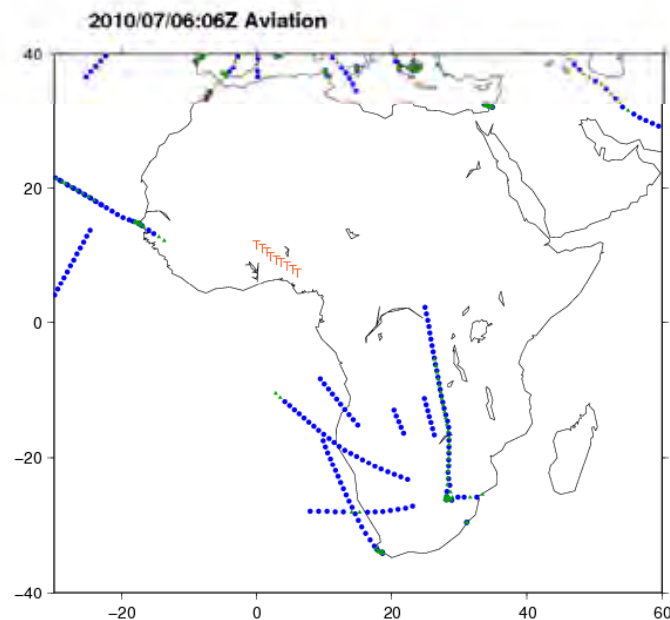
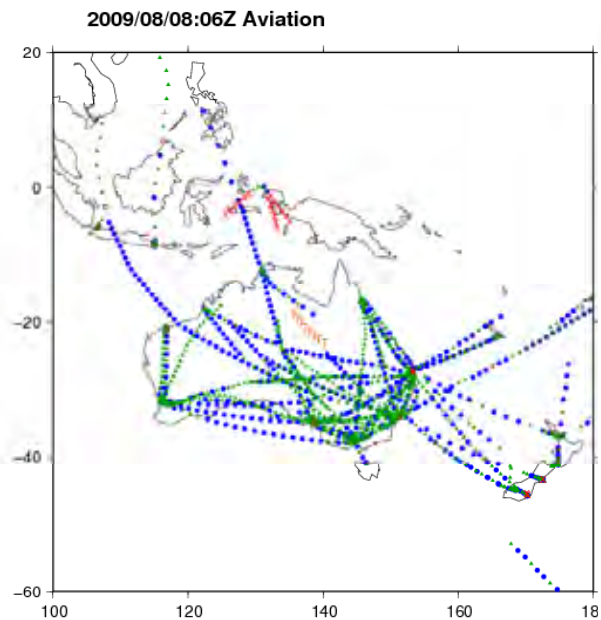
Check each obs

O-B are checked.

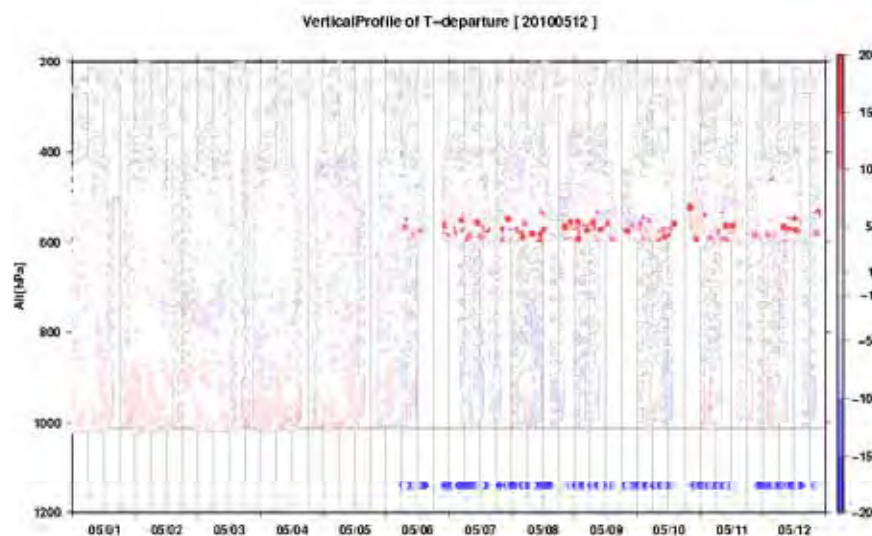




Recent status of Indian Radiosonde use.



Track-check error of Aircraft observation.



Temperature O-B profile of HLxxxx (xxxx : number).

NUMBER of REJECTED DATA (CDA)

2010 05 28 00UTC - 2010 07 07 18UTC

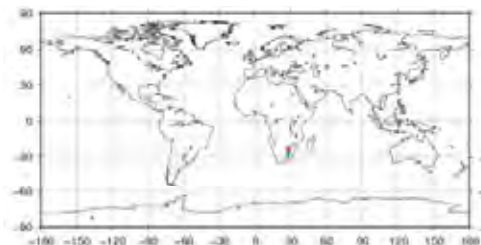
Global Analysis (Cycle, Early)

DataType: BUOY/PLATFORM

ImageSize: 640/480 y-range: auto

Plot kind:

- ☒ Reported of Cycle ☒ Rejected of Cycle ☒ Used of Cycle
☒ Reported of Early ☒ Rejected of Early ☒ Used of Early

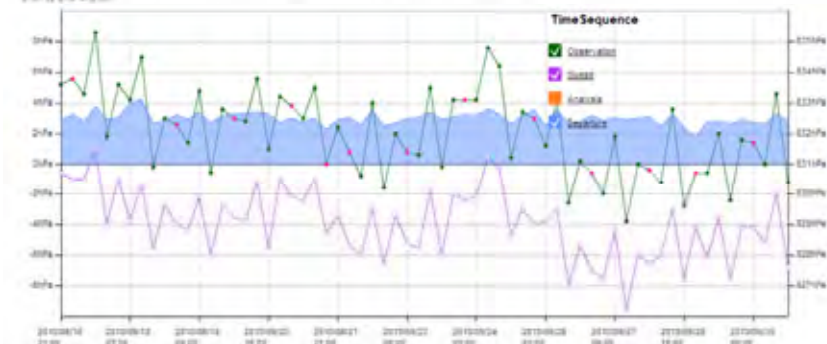


threshold = 2.5 MPa
update : 2010/07/02

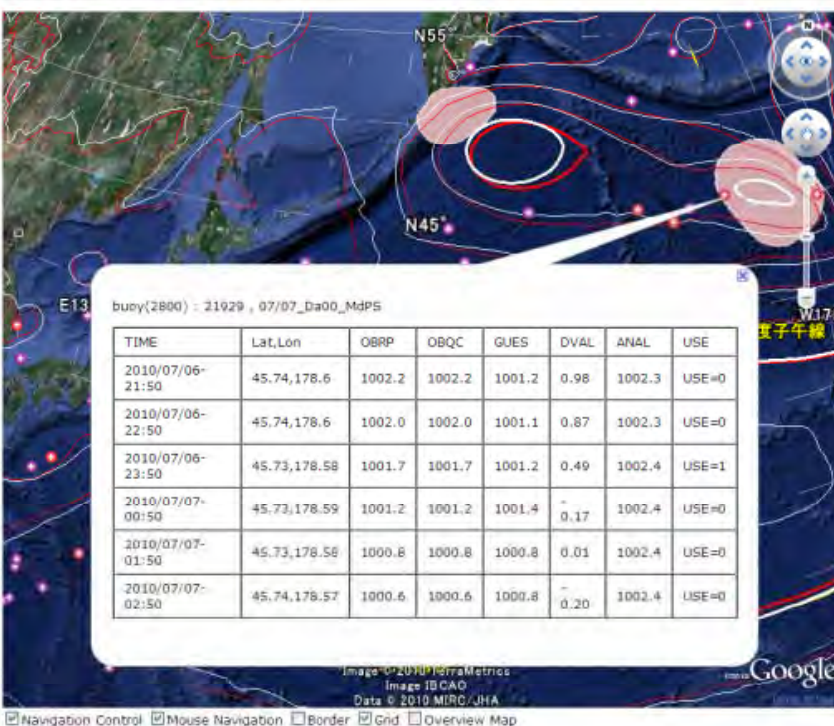
Station

☐ Data ☐ Cycle ☐ Rejected ☐ Early ☐ Report ☐ Error ☐ Error ☐ Error ☐ Error ☐ Error ☐ Error

plot by g2dmg.com



QC MONITOR 3D update :: 2010/07/08-02:16



buoy(2800) : 21929 , 07/07_Da00_MdP5

TIME	Lat, Lon	OBQP	OBQC	GUES	DVAL	ANAL	USE
2010/07/06-21:50	45.74, 178.6	1002.2	1002.2	1001.2	0.98	1002.3	USE=0
2010/07/06-22:50	45.74, 178.6	1002.0	1002.0	1001.1	0.87	1002.3	USE=0
2010/07/06-23:50	45.73, 178.58	1001.7	1001.7	1001.2	0.49	1002.4	USE=1
2010/07/07-00:50	45.73, 178.59	1001.2	1001.2	1001.4	0.17	1002.4	USE=0
2010/07/07-01:50	45.73, 178.56	1000.8	1000.8	1000.8	0.01	1002.4	USE=0
2010/07/07-02:50	45.74, 178.57	1000.6	1000.6	1000.8	0.20	1002.4	USE=0

☒ Navigation Control ☒ Mouse Navigation ☐ Border ☐ Gnd ☐ Overview Map

mean O-B map -- from 0704_00z to 0708_18z

ID: 4200

CALLION: EU0707

Pressure category	mean O-B (S) threshold (T)	mean O-B (S) threshold (SD)	mean O-B (S) threshold (FF)
h0 : 1000hPa < Pres < 1000hPa	0 < T < 1.0K	0 < T < 1.0K	0 < T < 1.0K
h1 : 950hPa < Pres < 1000hPa	-1.0K < T < -0.5K	-1.0K < T < -0.5K	-1.0K < T < -0.5K
h2 : 900hPa < Pres < 950hPa	-1.0K < T < -0.5K	-1.0K < T < -0.5K	-1.0K < T < -0.5K
h3 : 850hPa < Pres < 900hPa	-1.0K < T < -0.5K	-1.0K < T < -0.5K	-1.0K < T < -0.5K

*The number in the cell expresses the number of the report.

T (Temperature)																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																																							
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